

(相対論の力学)

$$(x^0, x^1, x^2, x^3) = (ct, x, y, z)$$

$$\begin{cases} ct' = \gamma ct - \gamma \beta x = \gamma (ct - \beta x) \\ x' = -\gamma \beta ct + \gamma x = \gamma (x - \beta ct) \\ y' = y \\ z' = z \end{cases} \quad \text{--- ①} \quad \begin{cases} \gamma = \frac{1}{\sqrt{1-\beta^2}} \\ \frac{v}{c} = \beta \end{cases}$$

$$\begin{bmatrix} ct' \\ x' \\ y' \\ z' \end{bmatrix} = \begin{bmatrix} \gamma & -\gamma\beta & 0 & 0 \\ -\gamma\beta & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} ct \\ x \\ y \\ z \end{bmatrix}$$

--- ② $\left[\begin{array}{l} v \text{ は } K \text{ 系に對する } K' \text{ 系} \\ \text{の速度 } x \text{ 軸の正の方向に移動} \\ \beta = \frac{v}{c} \end{array} \right]$

$$\begin{aligned} S'^2 &= (ct')^2 - x'^2 - y'^2 - z'^2 \\ &= \gamma^2 (ct - \beta x)^2 - \gamma^2 (x - \beta ct)^2 - y^2 - z^2 \end{aligned}$$

$$\gamma^2 \{ c^2 t^2 - 2c\beta xt + \beta^2 x^2 - x^2 + 2xv t - v^2 t^2 \} - y^2 - z^2$$

$$\gamma^2 \{ (c^2 - v^2) t^2 - (1 - \beta^2) x^2 \} - y^2 - z^2$$

$$\begin{aligned} &\gamma^2 c^2 (1 - \beta^2) t^2 - \gamma^2 (1 - \beta^2) x^2 - y^2 - z^2 \\ &= c^2 t^2 - x^2 - y^2 - z^2 \quad \text{--- ③} \end{aligned}$$

$$\therefore S'^2 = S^2 = (ct)^2 - x^2 - y^2 - z^2 = (-\text{定}) \quad \text{--- ④ Lorentz scalar}$$

$$dx^\mu dx_\mu = dx^\mu g_{\mu\nu} dx^\nu$$

$$\begin{aligned} ds^2 &= c^2 dt^2 - dx^2 - dy^2 - dz^2 = dx^\mu dx_\mu \\ &\quad \left(\begin{array}{l} \text{--- から } v \\ v^2 = v_x^2 + v_y^2 + v_z^2 \text{ 意味する} \end{array} \right) \quad \begin{array}{l} c^2 dt^2 - dx^2 - dy^2 - dz^2 \\ (c^2 - v^2) dt^2 \end{array} \quad \begin{array}{l} \text{--- } v \text{ は} \\ \text{物体の速} \\ \text{度 } K \text{ 系に對する} \end{array} \end{aligned}$$

粒子の S 系上での速度の
2乗を意味する

$$\begin{aligned} ds &= \sqrt{c^2 - v^2} dt \\ &= c \sqrt{1 - \frac{v^2}{c^2}} dt \end{aligned}$$

$$\boxed{d\tau = \frac{ds}{c} = \sqrt{1 - \frac{v^2}{c^2}} dt} \quad \text{--- ⑤ (固有時)}$$

四元速度の4元ベクトル

$$\frac{dx^\mu}{d\tau} = \left(\frac{c dt}{\sqrt{1-\beta^2}}, \frac{dx}{\sqrt{1-\beta^2}}, \frac{dy}{\sqrt{1-\beta^2}}, \frac{dz}{\sqrt{1-\beta^2}} \right) \quad \text{--- ⑦}$$

$$\begin{aligned} \frac{dx^\mu}{d\tau} &= \frac{dx^\mu}{\sqrt{1-\beta^2} dt} = \frac{1}{\sqrt{1-\beta^2}} \frac{dx^\mu}{dt} = \left(\frac{c}{\sqrt{1-\beta^2}}, \frac{1}{\sqrt{1-\beta^2}} \frac{dx}{dt}, \frac{1}{\sqrt{1-\beta^2}} \frac{dy}{dt}, \frac{1}{\sqrt{1-\beta^2}} \frac{dz}{dt} \right) \\ &= \left(\frac{c}{\sqrt{1-\beta^2}}, \frac{v_x}{\sqrt{1-\beta^2}}, \frac{v_y}{\sqrt{1-\beta^2}}, \frac{v_z}{\sqrt{1-\beta^2}} \right) \quad \text{--- ⑧} \end{aligned}$$

更に4元運動量も四元ベクトル

$$p^\mu = \frac{m_0}{\sqrt{1-\beta^2}} \frac{dx^\mu}{dt} = \left(\frac{m_0 c}{\sqrt{1-\beta^2}}, \frac{m_0 v_x}{\sqrt{1-\beta^2}}, \frac{m_0 v_y}{\sqrt{1-\beta^2}}, \frac{m_0 v_z}{\sqrt{1-\beta^2}} \right) \quad \text{--- ⑨}$$

$$\text{更に} \quad \frac{dp^\mu}{d\tau} = \frac{1}{\sqrt{1-\beta^2}} \frac{dp^\mu}{dt} \quad \text{--- ⑩}$$

$$= \frac{1}{\sqrt{1-\beta^2}} \frac{d}{dt} \left(\frac{m_0 c}{\sqrt{1-\beta^2}}, \frac{m_0 v_x}{\sqrt{1-\beta^2}}, \frac{m_0 v_y}{\sqrt{1-\beta^2}}, \frac{m_0 v_z}{\sqrt{1-\beta^2}} \right) \quad \text{--- ⑪}$$

$$\left. \begin{aligned} \frac{d}{dt} (m v_x) &= F_x \\ \frac{d}{dt} (m v_y) &= F_y \\ \frac{d}{dt} (m v_z) &= F_z \end{aligned} \right\} \quad \begin{array}{l} m = \frac{m_0}{\sqrt{1-\beta^2}} \text{ とおく} \\ \text{とあわせる} \end{array}$$

物体が x 軸方向に一定の力 F を受けて運動すると

$$\frac{d}{dt} \left(\frac{m_0}{\sqrt{1-\beta^2}} \frac{dx}{dt} \right) = F$$

$$m_0 \frac{d}{dt} \left[\frac{1}{\sqrt{1-\frac{v^2}{c^2}}} \frac{dx}{dt} \right] = F$$

示すから
異なる

$$\frac{dp^\mu}{d\tau} = \frac{1}{\sqrt{1-\beta^2}} \frac{d}{dt} (m c, m v_x, m v_y, m v_z) \quad \text{--- ⑫}$$

$$p^u = m_0 \frac{dx^u}{d\tau} = \frac{m_0}{\sqrt{1-\beta^2}} \frac{dx^u}{dt} \quad \text{--- ①}$$

$$x^u = (ct, x, y, z) + \text{const}$$

$$p^u = \left(\frac{m_0}{\sqrt{1-\beta^2}} \frac{d(ct)}{dt}, \frac{m_0}{\sqrt{1-\beta^2}} \frac{dx}{dt}, \frac{m_0}{\sqrt{1-\beta^2}} \frac{dy}{dt}, \frac{m_0}{\sqrt{1-\beta^2}} \frac{dz}{dt} \right)$$

$$p^u = \left(\frac{m_0 c}{\sqrt{1-\beta^2}}, \frac{m_0}{\sqrt{1-\beta^2}} \frac{dx}{dt}, \frac{m_0}{\sqrt{1-\beta^2}} \frac{dy}{dt}, \frac{m_0}{\sqrt{1-\beta^2}} \frac{dz}{dt} \right) \quad \text{--- ②}$$

空間部分について

(j=1, 2, 3)

$$\frac{d}{dt}(p^j) = F^j \quad \text{と おく}$$

$$\frac{d}{d\tau} p^j = \frac{1}{\sqrt{1-\beta^2}} \frac{d p^j}{dt} = \frac{F^j}{\sqrt{1-\beta^2}} \quad (j=1, 2, 3) \quad \text{--- ③}$$

$$p^u = \left(\frac{m_0 c}{\sqrt{1-\beta^2}}, \frac{m_0 v_x}{\sqrt{1-\beta^2}}, \frac{m_0 v_y}{\sqrt{1-\beta^2}}, \frac{m_0 v_z}{\sqrt{1-\beta^2}} \right)$$

$$\frac{d p^j}{d\tau} = \frac{1}{\sqrt{1-\beta^2}} \frac{d p^j}{dt}$$

$$\frac{d}{dt} \left(\frac{m_0}{\sqrt{1-\beta^2}} \right) = m_0 \frac{d}{dt} (1-\beta^2)^{-\frac{1}{2}} = -\frac{m_0}{2} (1-\beta^2)^{-\frac{3}{2}} \times \left(-\frac{2}{c^2} v_x \frac{dv_x}{dt} - \frac{2}{c^2} v_y \frac{dv_y}{dt} - \frac{2}{c^2} v_z \frac{dv_z}{dt} \right)$$

$$= \frac{m_0}{2} (1-\beta^2)^{-\frac{3}{2}} \times \left(\frac{2}{c^2} \right) \times (v_x \frac{dv_x}{dt} + v_y \frac{dv_y}{dt} + v_z \frac{dv_z}{dt})$$

$$\frac{d}{dt} \left(\frac{m_0}{\sqrt{1-\beta^2}} \right) = + \frac{m_0}{c^2} (1-\beta^2)^{-\frac{3}{2}} \cdot \vec{v} \cdot \frac{d\vec{v}}{dt}$$

$$c^2 \frac{d}{dt} \left(\frac{m_0}{\sqrt{1-\beta^2}} \right) = m_0 (1-\beta^2)^{-\frac{3}{2}} \vec{v} \cdot \frac{d\vec{v}}{dt} = \frac{m_0}{(\sqrt{1-\beta^2})^3} \vec{v} \cdot \frac{d\vec{v}}{dt}$$

$$\rightarrow \frac{d}{dt} \left(\frac{m_0 c^2}{\sqrt{1-\beta^2}} \right) = \frac{m_0}{(\sqrt{1-\beta^2})^3} \vec{v} \cdot \frac{d\vec{v}}{dt} = \vec{F} \cdot \vec{v} \quad (\text{エネルギー})$$

$$\frac{d}{dt} \left(\frac{m_0}{\sqrt{1-\beta^2}} \vec{v} \right) = \vec{F}$$

$$\vec{F} \cdot \vec{v} = \vec{v} \cdot \frac{d}{dt} \left(\frac{m_0}{\sqrt{1-\beta^2}} \vec{v} \right)$$

$$= \vec{v} \cdot \frac{d}{dt} \left(\frac{m_0}{\sqrt{1-\beta^2}} \right) \vec{v} + \vec{v} \cdot \frac{m_0}{\sqrt{1-\beta^2}} \frac{d\vec{v}}{dt}$$

$$= \vec{v} \cdot \left\{ \frac{m_0}{c^2} (1-\beta^2)^{-\frac{3}{2}} \vec{v} \cdot \frac{d\vec{v}}{dt} \right\} \vec{v} + \frac{m_0}{\sqrt{1-\beta^2}} \vec{v} \cdot \frac{d\vec{v}}{dt}$$

$$= \frac{m_0}{c^2} (1-\beta^2)^{-\frac{3}{2}} v^2 \frac{d\vec{v}}{dt} \cdot \vec{v} + \frac{m_0}{\sqrt{1-\beta^2}} \vec{v} \cdot \frac{d\vec{v}}{dt}$$

$$= \frac{m_0}{\sqrt{1-\beta^2}} \cdot \frac{1}{(1-\beta^2)} \frac{v^2}{c^2} \frac{d\vec{v}}{dt} \cdot \vec{v} + \frac{m_0}{\sqrt{1-\beta^2}} \vec{v} \cdot \frac{d\vec{v}}{dt}$$

$$\frac{m_0}{\sqrt{1-\beta^2}} \frac{1}{(1-\beta^2)} \beta^2 \cdot \vec{v} \cdot \frac{d\vec{v}}{dt} + \frac{m_0}{\sqrt{1-\beta^2}} \vec{v} \cdot \frac{d\vec{v}}{dt}$$

$$= \frac{m_0}{\sqrt{1-\beta^2}} \left\{ \frac{1}{1-\beta^2} \beta^2 + 1 \right\} \vec{v} \cdot \frac{d\vec{v}}{dt}$$

$$= \frac{m_0}{\sqrt{1-\beta^2}} \left\{ \frac{\beta^2}{1-\beta^2} + \frac{1-\beta^2}{1-\beta^2} \right\} \vec{v} \cdot \frac{d\vec{v}}{dt}$$

$$= \frac{m_0}{\sqrt{1-\beta^2}} \frac{1}{1-\beta^2} \vec{v} \cdot \frac{d\vec{v}}{dt} = \frac{m_0}{(\sqrt{1-\beta^2})^3} \vec{v} \cdot \frac{d\vec{v}}{dt}$$

(前N-ジョリ)

$$\vec{F} \cdot \vec{v} = \frac{m_0}{(\sqrt{1-\beta^2})^3} \vec{v} \cdot \frac{d\vec{v}}{dt} = \frac{d}{dt} \left(\frac{m_0 c^2}{\sqrt{1-\beta^2}} \right)$$

$$\therefore \frac{\vec{F}}{\sqrt{1-\beta^2}} \cdot \vec{v} = \frac{1}{\sqrt{1-\beta^2}} \frac{d}{dt} \left(\frac{m_0 c^2}{\sqrt{1-\beta^2}} \right)$$

$$= \frac{d}{dt} \left(\frac{m_0 c^2}{\sqrt{1-\beta^2}} \right) = \frac{d}{dt} \left(\frac{E}{c} \right)$$

$$\therefore \frac{\vec{F} \cdot \vec{v}}{c \sqrt{1-\beta^2}} = \frac{d}{dt} \left(\frac{m_0 c}{\sqrt{1-\beta^2}} \right)$$

$$E = \frac{m_0 c^2}{\sqrt{1-\beta^2}} \text{ とき } \rightarrow \vec{F} \cdot \vec{v} = \frac{dE}{dt} \quad \frac{E}{c} = \frac{m_0 c}{\sqrt{1-\beta^2}} \text{ とき }$$

(Eは仕事、次元よりエネルギーを表わすと理解出来る)

$$p^\mu = \left(\frac{E}{c}, \frac{m_0}{\sqrt{1-\beta^2}} \frac{dx}{dt}, \frac{m_0}{\sqrt{1-\beta^2}} \frac{dy}{dt}, \frac{m_0}{\sqrt{1-\beta^2}} \frac{dz}{dt} \right)$$

$$p^\mu = \left(\frac{E}{c}, p_x, p_y, p_z \right)$$

$$\begin{cases} p_x = m \frac{dx}{dt} \\ p_y = m \frac{dy}{dt} \\ p_z = m \frac{dz}{dt} \end{cases} \quad m = \frac{m_0}{\sqrt{1-\beta^2}}$$

 p^μ は四元運動量 (ローレンツ変換に従う物理量) $p^\mu p_\mu = \text{一定 (スカラー)}$ である (ローレンツ変換に従う物理量はローレンツ積は一定である)

$$\frac{E^2}{c^2} - p_x^2 - p_y^2 - p_z^2 = (\text{一定})$$

$$\frac{E^2}{c^2} - p^2 = \frac{E_0^2}{c^2} \quad E_0 = m_0 c^2$$

$$\frac{E^2}{c^2} - p^2 = \frac{m_0^2 c^4}{c^2} = m_0^2 c^2$$

$$\frac{E^2}{c^2} = p^2 + m_0^2 c^2$$

$$E^2 = c^2 p^2 + m_0^2 c^4$$

$$E = \sqrt{c^2 p^2 + m_0^2 c^4}$$

$$m_0 = 0 \text{ とき } E = cp \quad p = \frac{E}{c}$$