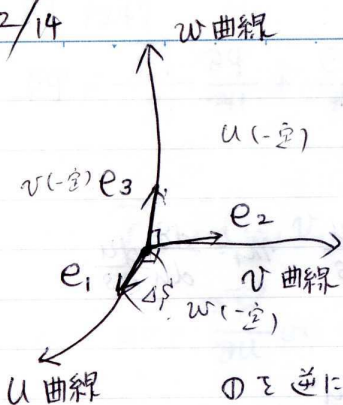


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 $u(-定)$

$$u = u(x, y, z) \quad v = v(x, y, z) \quad w = w(x, y, z)$$

①

$$(x, y, z) \xrightarrow{1対1} (u, v, w) \quad \text{③}$$

u 曲線 $\Rightarrow$ ②を逆に解いて

$$x = x(u, v, w) \quad y = y(u, v, w) \quad z = z(u, v, w)$$

u 方向のベクトル $\rightarrow$ (uの値が増加する) 方向にある

$$\vec{u} = \left(\frac{\partial x}{\partial u}, \frac{\partial y}{\partial u}, \frac{\partial z}{\partial u} \right)$$

$$e_1 = \frac{1}{\sqrt{\left(\frac{\partial x}{\partial u}\right)^2 + \left(\frac{\partial y}{\partial u}\right)^2 + \left(\frac{\partial z}{\partial u}\right)^2}} \left(\frac{\partial x}{\partial u}, \frac{\partial y}{\partial u}, \frac{\partial z}{\partial u} \right) = \frac{\vec{u}}{h_1}$$

$$h_1 = \sqrt{\left(\frac{\partial x}{\partial u}\right)^2 + \left(\frac{\partial y}{\partial u}\right)^2 + \left(\frac{\partial z}{\partial u}\right)^2}$$

$$\nabla u = \frac{\partial u}{\partial x} i + \frac{\partial u}{\partial y} j + \frac{\partial u}{\partial z} k \quad (u \text{ 平面に対して垂直, } u \text{ の増加する向き})$$

u 平面の法線 $\vec{n}_1$
(u=一定) ベクトル

$$\vec{n}_1 = \frac{\nabla u}{|\nabla u|} = \frac{\nabla u}{\sqrt{\left(\frac{\partial u}{\partial x}\right)^2 + \left(\frac{\partial u}{\partial y}\right)^2 + \left(\frac{\partial u}{\partial z}\right)^2}}$$

$$|\nabla u| = \frac{\Delta u}{\Delta S}$$

法線方向の微係数

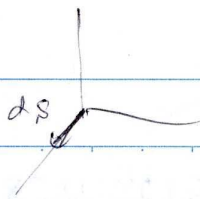
$$\nabla u = |\text{grad } u| \cdot \vec{n}_1$$

$$\nabla u = |\text{grad } u| \cdot \frac{\vec{u}}{h_1}$$

$$\vec{e}_1 \times \nabla u = 0 \quad \text{これは垂直}$$

$$\left(\frac{\partial y}{\partial u} \frac{\partial u}{\partial z} - \frac{\partial z}{\partial u} \frac{\partial u}{\partial y} \right)$$

$$h_1 = |\text{grad } u|$$



$$l_1 = \frac{dx}{ds} = \frac{dx}{du} \cdot \frac{du}{ds} \quad m_1 = \frac{dy}{ds} = \frac{dy}{du} \cdot \frac{du}{ds} \quad n_1 = \frac{dz}{ds} = \frac{dz}{du} \cdot \frac{du}{ds}$$

$$ds = \sqrt{\left(\frac{\partial x}{\partial u}\right)^2 du^2 + \left(\frac{\partial y}{\partial u}\right)^2 du^2 + \left(\frac{\partial z}{\partial u}\right)^2 du^2}$$

$$= \sqrt{\left(\frac{\partial x}{\partial u}\right)^2 + \left(\frac{\partial y}{\partial u}\right)^2 + \left(\frac{\partial z}{\partial u}\right)^2} du$$

$$\frac{ds}{du} = h_1$$

$$\frac{du}{ds} = \frac{1}{h_1}$$

$$l_1 = \frac{1}{h_1} \frac{\partial x}{\partial u} \quad m_1 = \frac{1}{h_1} \frac{\partial y}{\partial u} \quad n_1 = \frac{1}{h_1} \frac{\partial z}{\partial u}$$

$$e_1 = \frac{1}{h_1} \left(\frac{\partial x}{\partial u}, \frac{\partial y}{\partial u}, \frac{\partial z}{\partial u} \right)$$

u方向のs

$$\frac{\partial x}{\partial u} \quad \frac{\partial x}{\partial u} \times \frac{\partial}{\partial u}$$

$$\frac{ds}{du} = h_1 \quad \frac{du}{ds} = \frac{1}{h_1}$$

~~u方向のs~~ ~~u方向のs~~ ~~u方向のs~~

法線方向の

$$\frac{1}{h_1}$$

$$\nabla u = \frac{1}{h_1} \vec{u} \quad \vec{u} = h_1 \nabla u$$

(u, v, w)

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$$\nabla \varphi = \frac{\vec{e}_1}{h_1} \frac{\partial \varphi}{\partial u} + \frac{\vec{e}_2}{h_2} \frac{\partial \varphi}{\partial v} + \frac{\vec{e}_3}{h_3} \frac{\partial \varphi}{\partial w} \quad (\text{証明せよ})$$

$$\vec{r} = \vec{r}(u, v, w) \text{ とし}$$

$$d\vec{r} = \frac{\partial \vec{r}}{\partial u} du + \frac{\partial \vec{r}}{\partial v} dv + \frac{\partial \vec{r}}{\partial w} dw \quad \text{--- ①}$$

$$\nabla \varphi = f_1 \vec{e}_1 + f_2 \vec{e}_2 + f_3 \vec{e}_3 \text{ とおくと --- ②}$$

$$d\varphi = \nabla \varphi \cdot d\vec{r} \quad \text{--- ③}$$

$$\frac{\partial \vec{r}}{\partial u} = h_1 \vec{e}_1 \quad \frac{\partial \vec{r}}{\partial v} = h_2 \vec{e}_2 \quad \frac{\partial \vec{r}}{\partial w} = h_3 \vec{e}_3 \quad \text{--- ④}$$

④を③に代入

$$d\vec{r} = h_1 \vec{e}_1 du + h_2 \vec{e}_2 dv + h_3 \vec{e}_3 dw \quad \text{--- ⑤}$$

$$d\varphi = (f_1 \vec{e}_1 + f_2 \vec{e}_2 + f_3 \vec{e}_3)(h_1 du \vec{e}_1 + h_2 dv \vec{e}_2 + h_3 dw \vec{e}_3) \quad \text{--- ⑥}$$

$$= f_1 h_1 du + f_2 h_2 dv + f_3 h_3 dw \quad \text{--- ⑦}$$

$$\text{全微分より} \quad = \frac{\partial \varphi}{\partial u} du + \frac{\partial \varphi}{\partial v} dv + \frac{\partial \varphi}{\partial w} dw \quad \text{--- ⑧}$$

⑦⑧の比較

$$\frac{\partial \varphi}{\partial u} = f_1 h_1 \quad \frac{\partial \varphi}{\partial v} = f_2 h_2 \quad \frac{\partial \varphi}{\partial w} = f_3 h_3 \quad \text{--- ⑨}$$

$$f_1 = \frac{1}{h_1} \frac{\partial \varphi}{\partial u} \quad f_2 = \frac{1}{h_2} \frac{\partial \varphi}{\partial v} \quad f_3 = \frac{1}{h_3} \frac{\partial \varphi}{\partial w} \quad \text{--- ⑩}$$

⑩を⑧に代入

$$\nabla \varphi = \frac{1}{h_1} \frac{\partial \varphi}{\partial u} \vec{e}_1 + \frac{1}{h_2} \frac{\partial \varphi}{\partial v} \vec{e}_2 + \frac{1}{h_3} \frac{\partial \varphi}{\partial w} \vec{e}_3 \quad (\text{おわり})$$

$u(u, v, w)$
 (u, v, w) は独立変数の座標

 $\varphi = u$

$$\nabla \varphi = \frac{1}{h_1} \frac{\partial \varphi}{\partial u} \vec{e}_1 + \frac{1}{h_2} \frac{\partial \varphi}{\partial v} \vec{e}_2 + \frac{1}{h_3} \frac{\partial \varphi}{\partial w} \vec{e}_3$$

$$\varphi = u \text{ に対して } \left(\frac{\vec{e}_1}{h_1} \frac{\partial}{\partial u} + \frac{\vec{e}_2}{h_2} \frac{\partial}{\partial v} + \frac{\vec{e}_3}{h_3} \frac{\partial}{\partial w} \right) \varphi$$

$$\nabla u = \frac{1}{h_1} \frac{\partial u}{\partial u} \vec{e}_1 = \frac{1}{h_1} \vec{e}_1$$

$$\vec{e}_1 = h_1 \nabla u$$

$$\nabla v = \frac{1}{h_2} \frac{\partial v}{\partial v} \vec{e}_2 = \frac{1}{h_2} \vec{e}_2$$

$$\vec{e}_2 = h_2 \nabla v$$

$$\nabla w = \frac{1}{h_3} \frac{\partial w}{\partial w} \vec{e}_3 = \frac{1}{h_3} \vec{e}_3$$

$$\vec{e}_3 = h_3 \nabla w$$

$$h_1 = \frac{1}{|\nabla u|} \quad h_2 = \frac{1}{|\nabla v|} \quad h_3 = \frac{1}{|\nabla w|}$$

 $\vec{e}_1, \vec{e}_2, \vec{e}_3$ は単位ベクトル

$$|\nabla u| = \frac{du}{ds_1} \longrightarrow ds_1 = \frac{1}{|\nabla u|} du$$

$$= h_1 du$$

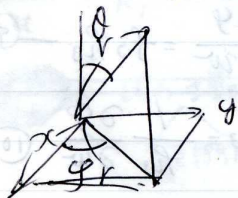
$$|\nabla w| = \frac{dw}{ds_3} \longrightarrow$$

$$ds_2 = \frac{1}{|\nabla v|} dv = h_2 dv$$

$$|\nabla v| = \frac{dv}{ds_2} \longrightarrow$$

$$ds_3 = \frac{1}{|\nabla w|} dw = h_3 dw$$

$$ds^2 = ds_1^2 + ds_2^2 + ds_3^2$$



$$x = r \sin \theta \cos \varphi$$

$$y = r \sin \theta \sin \varphi$$

$$z = r \cos \theta$$

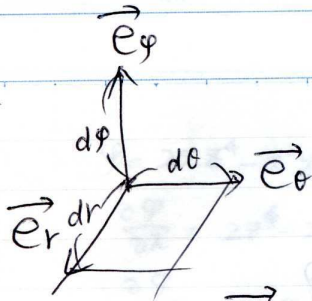
$$\frac{\partial x}{\partial r} = \sin \theta \cos \varphi$$

$$\frac{\partial y}{\partial r} = \sin \theta \sin \varphi$$

$$\frac{\partial z}{\partial r} = \cos \theta$$

$$h_1 = \sqrt{\sin^2 \theta \cos^2 \varphi + \sin^2 \theta \sin^2 \varphi + \cos^2 \theta}$$

$$= \frac{1}{h_1} \frac{\partial}{\partial r}$$



$$dS_r =$$

$$\vec{e}_r = \frac{\nabla u}{h_1}$$

$$\frac{\partial \vec{r}}{\partial r} = \vec{e}_r$$

$$\frac{\partial \vec{r}}{\partial r} = h_1 \vec{e}_r$$

$$\frac{\partial \vec{r}}{\partial \theta} = h_2 \vec{e}_\theta$$

$$\frac{\partial \vec{r}}{\partial \phi} = h_3 \vec{e}_\phi$$

$$\vec{e}_r = \frac{1}{h_1} \frac{\partial \vec{r}}{\partial r}$$

$$\vec{e}_\theta = \frac{1}{h_2} \frac{\partial \vec{r}}{\partial \theta}$$

$$\vec{e}_\phi = \frac{1}{h_3} \frac{\partial \vec{r}}{\partial \phi}$$

$$\left| \frac{\partial \vec{r}}{\partial r} \right| = h_1 \quad \left| \frac{\partial \vec{r}}{\partial \theta} \right| = h_2 \quad \left| \frac{\partial \vec{r}}{\partial \phi} \right| = h_3$$

$$= 1 \quad = r \quad = r \sin \theta$$

$$dS_1 = |\partial \vec{r}| dr = h_1 dr \quad dS_2 = |\partial \vec{r}| d\theta = h_2 d\theta \quad dS_3 = |\partial \vec{r}| d\phi = h_3 d\phi$$

$$dS_1 = h_1 dr \quad dS_2 = h_2 d\theta \quad dS_3 = h_3 d\phi$$

$$= dr \quad dS_2 = r d\theta \quad dS_3 = r \sin \theta d\phi$$

$$dV = dS_1 dS_2 dS_3 = r^2 \sin \theta dr d\theta d\phi$$

$$\frac{1}{h_1} \frac{\partial x}{\partial u_1} = h_1 \frac{\partial u_1}{\partial x}$$

$$\frac{\partial x}{\partial u_1} = h_1^2 \frac{\partial u_1}{\partial x}$$

$$\frac{\partial y}{\partial u_1} = h_1^2 \frac{\partial u_1}{\partial y}$$

$$\frac{\partial z}{\partial u_1} = h_1^2 \frac{\partial u_1}{\partial z}$$

$$\frac{\partial x}{\partial u_1} \vec{i} + \frac{\partial y}{\partial u_1} \vec{j} + \frac{\partial z}{\partial u_1} \vec{k} = h_1^2 \left(\frac{\partial u_1}{\partial x} \vec{i} + \frac{\partial u_1}{\partial y} \vec{j} + \frac{\partial u_1}{\partial z} \vec{k} \right)$$

$$\frac{\partial \vec{r}}{\partial u_1} = h_1^2 \nabla u_1 \quad \frac{\partial \vec{r}}{\partial u_2} = h_2^2 \nabla u_2 \quad \frac{\partial \vec{r}}{\partial u_3} = h_3^2 \nabla u_3$$

$$\nabla \cdot (A \vec{e}_1)$$

$$\nabla u_1 = \frac{\vec{e}_1}{h_1} \quad \nabla u_2 = \frac{\vec{e}_2}{h_2} \quad \nabla u_3 = \frac{\vec{e}_3}{h_3}$$

$$\left(\frac{\partial \vec{r}}{\partial u_1} = \vec{e}_1 \quad \frac{\partial \vec{r}}{\partial u_2} = \vec{e}_2 \quad \frac{\partial \vec{r}}{\partial u_3} = \vec{e}_3 \right)$$

$$\frac{\partial \vec{r}}{\partial u_1} = h_1 \vec{e}_1 \quad \frac{\partial \vec{r}}{\partial u_2} = h_2 \vec{e}_2 \quad \frac{\partial \vec{r}}{\partial u_3} = h_3 \vec{e}_3$$

$$\vec{e}_1 = \frac{1}{h_1} \frac{\partial \vec{r}}{\partial u_1} =$$

$$= \frac{1}{h_1} \left(\frac{\partial x}{\partial u_1} \vec{i} + \frac{\partial y}{\partial u_1} \vec{j} + \frac{\partial z}{\partial u_1} \vec{k} \right)$$

$$\vec{e}_1 = \left(\frac{1}{h_1} \frac{\partial x}{\partial u_1}, \frac{1}{h_1} \frac{\partial y}{\partial u_1}, \frac{1}{h_1} \frac{\partial z}{\partial u_1} \right)$$

$$\vec{e}_2 = \left(\frac{1}{h_2} \frac{\partial x}{\partial u_2}, \frac{1}{h_2} \frac{\partial y}{\partial u_2}, \frac{1}{h_2} \frac{\partial z}{\partial u_2} \right)$$

$$\vec{e}_3 = \left(\frac{1}{h_3} \frac{\partial x}{\partial u_3}, \frac{1}{h_3} \frac{\partial y}{\partial u_3}, \frac{1}{h_3} \frac{\partial z}{\partial u_3} \right)$$

$$\vec{e}_1 = h_1 \nabla u_1 = \left(\cancel{h_1 \frac{\partial x}{\partial u_1}}, \cancel{h_1 \frac{\partial y}{\partial u_1}}, \cancel{h_1 \frac{\partial z}{\partial u_1}} \right)$$

$$= \left(h_1 \frac{\partial u_1}{\partial x}, h_1 \frac{\partial u_1}{\partial y}, h_1 \frac{\partial u_1}{\partial z} \right)$$

$$\vec{e}_2 = h_2 \nabla u_2 = \left(h_2 \frac{\partial u_2}{\partial x}, h_2 \frac{\partial u_2}{\partial y}, h_2 \frac{\partial u_2}{\partial z} \right)$$

$$\vec{e}_3 = h_3 \nabla u_3 = \left(h_3 \frac{\partial u_3}{\partial x}, h_3 \frac{\partial u_3}{\partial y}, h_3 \frac{\partial u_3}{\partial z} \right)$$

$$\vec{e}_1 \cdot \vec{e}_2 = 0$$

$$\frac{1}{h_1 h_2} \left(\frac{\partial x}{\partial u_1} \frac{\partial x}{\partial u_2} + \frac{\partial y}{\partial u_1} \frac{\partial y}{\partial u_2} + \frac{\partial z}{\partial u_1} \frac{\partial z}{\partial u_2} \right) = 0$$

$$\vec{e}_1 \cdot \vec{e}_3 = 0$$

$$\frac{1}{h_1 h_3} \left(\frac{\partial x}{\partial u_1} \frac{\partial x}{\partial u_3} + \frac{\partial y}{\partial u_1} \frac{\partial y}{\partial u_3} + \frac{\partial z}{\partial u_1} \frac{\partial z}{\partial u_3} \right) = 0$$

$$\vec{e}_2 \cdot \vec{e}_3 = \frac{1}{h_2 h_3} \left(\frac{\partial x}{\partial u_2} \frac{\partial x}{\partial u_3} + \frac{\partial y}{\partial u_2} \frac{\partial y}{\partial u_3} + \frac{\partial z}{\partial u_2} \frac{\partial z}{\partial u_3} \right) = 0$$

$$\sum_{k=1}^3 \frac{\partial g_k}{\partial u_i} \frac{\partial g_k}{\partial u_j} = 0$$

$$g_1 = x \quad g_2 = y \quad g_3 = z$$

$$\vec{e}_1 \times \vec{e}_2 = \vec{e}_3$$

$$\nabla u_1 = \frac{\vec{e}_1}{h_1} \quad \nabla u_2 = \frac{\vec{e}_2}{h_2} \quad \nabla u_3 = \frac{\vec{e}_3}{h_3}$$

$$\nabla u_1 \times \nabla u_2 = \frac{\vec{e}_1}{h_1} \times \frac{\vec{e}_2}{h_2} = \frac{\vec{e}_3}{h_1 h_2} = \frac{h_3}{h_1 h_2} \nabla u_3$$

$$\nabla u_2 \times \nabla u_3 = \frac{\vec{e}_2}{h_2} \times \frac{\vec{e}_3}{h_3} = \frac{\vec{e}_1}{h_2 h_3} = \frac{h_1}{h_2 h_3} \nabla u_1$$

$$\vec{e}_1 = h_2 h_3 (\nabla u_2 \times \nabla u_3)$$

$$\vec{\nabla} \cdot \vec{A} = \frac{1}{h_1 h_2 h_3} \left[\frac{\partial}{\partial u_1} \left(\frac{h_2 h_3}{h_1} \frac{\partial \psi}{\partial u_1} \right) + \frac{\partial}{\partial u_2} \left(\frac{h_3 h_1}{h_2} \frac{\partial \psi}{\partial u_2} \right) + \frac{\partial}{\partial u_3} \left(\frac{h_1 h_2}{h_3} \frac{\partial \psi}{\partial u_3} \right) \right]$$

$$\vec{A} = A_1 \vec{e}_1 + A_2 \vec{e}_2 + A_3 \vec{e}_3$$

$$\nabla(A_1 \vec{e}_1)$$

$$= \nabla [A_1 h_2 h_3 (\nabla u_2 \times \nabla u_3)]$$

$$= \nabla(A_1 h_2 h_3) \cdot (\nabla u_2 \times \nabla u_3) + A_1 h_2 h_3 \nabla(\nabla u_2 \times \nabla u_3)$$

$$= \nabla(A_1 h_2 h_3) \cdot (\nabla u_2 \times \nabla u_3)$$

$$+ A_1 h_2 h_3 \{ [\nabla \times (\nabla u_2)] \cdot \nabla u_3 - [\nabla \times (\nabla u_3)] \cdot \nabla u_2 \}$$

$$= \nabla(A_1 h_2 h_3) \cdot (\nabla u_2 \times \nabla u_3) = \nabla(A_1 h_2 h_3) \frac{\vec{e}_1}{h_2 h_3}$$

$$= \left(\frac{\vec{e}_1}{h_1} \frac{\partial}{\partial u_1} (A_1 h_2 h_3) + \frac{\vec{e}_2}{h_2} \frac{\partial}{\partial u_2} (A_1 h_2 h_3) + \frac{\vec{e}_3}{h_3} \frac{\partial}{\partial u_3} (A_1 h_2 h_3) \right) \cdot \frac{\vec{e}_1}{h_2 h_3}$$

$$= \frac{1}{h_1 h_2 h_3} \frac{\partial}{\partial u_1} (A_1 h_2 h_3)$$

$$\nabla(A_2 \vec{e}_2) = \frac{1}{h_1 h_2 h_3} \frac{\partial}{\partial u_2} (A_2 h_3 h_1)$$

$$\nabla(A_3 \vec{e}_3) = \frac{1}{h_1 h_2 h_3} \frac{\partial}{\partial u_3} (A_3 h_1 h_2)$$

$$\nabla \cdot \vec{A} = \nabla(A_1 \vec{e}_1 + A_2 \vec{e}_2 + A_3 \vec{e}_3)$$

$$= \frac{1}{h_1 h_2 h_3} \left[\frac{\partial}{\partial u_1} (A_1 h_2 h_3) + \frac{\partial}{\partial u_2} (A_2 h_3 h_1) + \frac{\partial}{\partial u_3} (A_3 h_1 h_2) \right]$$

$$\vec{A} = \nabla \varphi = \frac{\partial \varphi}{\partial u_1} \vec{e}_1 + \frac{1}{h_2} \frac{\partial \varphi}{\partial u_2} \vec{e}_2 + \frac{1}{h_3} \frac{\partial \varphi}{\partial u_3} \vec{e}_3$$

$$A_1 = \frac{1}{h_1} \frac{\partial \varphi}{\partial u_1} \quad A_2 = \frac{1}{h_2} \frac{\partial \varphi}{\partial u_2} \quad A_3 = \frac{1}{h_3} \frac{\partial \varphi}{\partial u_3}$$

$$\nabla \times (A_1 \vec{e}_1)$$

$$\nabla \times (A_1 h_1 \nabla u_1)$$

$$= \nabla (A_1 h_1) \times \nabla u_1 + A_1 h_1 \nabla \times \nabla u_1$$

$$= \left(\vec{e}_1 \frac{1}{h_1} \frac{\partial (A_1 h_1)}{\partial u_1} + \vec{e}_2 \frac{1}{h_2} \frac{\partial (A_1 h_1)}{\partial u_2} + \vec{e}_3 \frac{1}{h_3} \frac{\partial (A_1 h_1)}{\partial u_3} \right) \times \vec{e}_1$$

$$= \vec{e}_2 \times \vec{e}_1 \frac{1}{h_1 h_2} \frac{\partial (A_1 h_1)}{\partial u_2} + \vec{e}_3 \times \vec{e}_1 \frac{1}{h_3 h_1} \frac{\partial (A_1 h_1)}{\partial u_3}$$

$$= \vec{e}_2 \frac{1}{h_3 h_1} \frac{\partial (A_1 h_1)}{\partial u_3} - \vec{e}_3 \frac{1}{h_1 h_2} \frac{\partial (A_1 h_1)}{\partial u_2} \quad \text{--- (1)}$$

$$\nabla \times (A_2 \vec{e}_2)$$

$$= \vec{e}_3 \frac{1}{h_1 h_2} \frac{\partial (A_2 h_2)}{\partial u_1} - \vec{e}_1 \frac{1}{h_2 h_3} \frac{\partial (A_2 h_2)}{\partial u_3} \quad \text{--- (2)}$$

$$\nabla \times (A_3 \vec{e}_3)$$

$$= \vec{e}_1 \frac{1}{h_2 h_3} \frac{\partial (A_3 h_3)}{\partial u_2} - \vec{e}_2 \frac{1}{h_3 h_1} \frac{\partial (A_3 h_3)}{\partial u_1} \quad \text{--- (3)}$$

$$\nabla \times (A_1 \vec{e}_1 + A_2 \vec{e}_2 + A_3 \vec{e}_3)$$

$$= \vec{e}_1 \left\{ \frac{1}{h_2 h_3} \frac{\partial (A_3 h_3)}{\partial u_2} - \frac{1}{h_2 h_3} \frac{\partial (A_2 h_2)}{\partial u_3} \right\} \\ + \vec{e}_2 \left\{ \frac{1}{h_3 h_1} \frac{\partial (A_1 h_1)}{\partial u_3} - \frac{1}{h_3 h_1} \frac{\partial (A_3 h_3)}{\partial u_1} \right\} \\ + \vec{e}_3 \left\{ \frac{1}{h_1 h_2} \frac{\partial (A_2 h_2)}{\partial u_1} - \frac{1}{h_1 h_2} \frac{\partial (A_1 h_1)}{\partial u_2} \right\}$$

$$\nabla \cdot \vec{A} = \frac{1}{h_1 h_2 h_3} \left(\frac{\partial}{\partial u_1} (A_1 h_2 h_3) + \frac{\partial}{\partial u_2} (A_2 h_3 h_1) + \frac{\partial}{\partial u_3} (A_3 h_1 h_2) \right)$$

$$\vec{A} = \nabla \varphi = \vec{e}_1 \cdot \underbrace{\frac{1}{h_1} \frac{\partial \varphi}{\partial u_1}}_{A_1} + \vec{e}_2 \cdot \underbrace{\frac{1}{h_2} \frac{\partial \varphi}{\partial u_2}}_{A_2} + \vec{e}_3 \cdot \underbrace{\frac{1}{h_3} \frac{\partial \varphi}{\partial u_3}}_{A_3}$$

とある

$$\nabla \cdot \vec{A} = \nabla^2 \varphi = \frac{1}{h_1 h_2 h_3} \left(\frac{\partial}{\partial u_1} \left(\frac{h_2 h_3}{h_1} \frac{\partial \varphi}{\partial u_1} \right) + \frac{\partial}{\partial u_2} \left(\frac{h_3 h_1}{h_2} \frac{\partial \varphi}{\partial u_2} \right) + \frac{\partial}{\partial u_3} \left(\frac{h_1 h_2}{h_3} \frac{\partial \varphi}{\partial u_3} \right) \right)$$

$$(u_1, u_2, u_3) \rightarrow (r, \theta, \varphi)$$

$$h_1 = 1 \quad h_2 = r \quad h_3 = r \sin \theta \quad h_1 h_2 h_3 = r^2 \sin \theta$$

$$\nabla^2 \varphi = \frac{1}{r^2 \sin \theta} \left[\frac{\partial}{\partial r} \left(r^2 \sin \theta \frac{\partial \varphi}{\partial r} \right) + \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial \varphi}{\partial \theta} \right) + \frac{\partial}{\partial \varphi} \left(\frac{1}{\sin \theta} \frac{\partial \varphi}{\partial \varphi} \right) \right]$$